VASAVI COLLEGE OF ENGINEERING(AUTONOMOUS) Ibrahimbagh, Hyderabad-31

Approved by A.I.C.T.E., New Delhi and Affiliated to Osmania University, Hyderabad-07

Sponsored by VASAVI ACADEMY OF EDUCATION Hyderabad



SYLLABI UNDER CBCS FOR B.E VII & VIII SEMESTERS OF MECHANICAL ENGINEERING (R-21) WITH EFFECT FROM 2024-25 (For the students admitted in 2021-22)



DEPARTMENT OF MECHANICAL ENGINEERING

+91-40-23146060, 23146061 Fax: +91-40-23146090 Website: <u>www.vce.ac.in</u>

VISION OF THE INSTITUTE

Striving for a symbiosis of technological excellence and human values.

MISSION OF THE INSTITUTE

To arm young brains with competitive technology and nurture holistic development of the individuals for a better tomorrow.

VISION OF THE DEPARTMENT

To establish global leadership in the field of mechanical engineering and develop competent human resources with values and ethics

MISSION OF THE DEPARTMENT

To *nurture* an environment of research, innovation and knowledge through the latest teaching-learning practices in mechanical engineering

PRC	OGRAM OUTCOMES (POs)
1	Graduates demonstrate knowledge of basic sciences and mechanical engineering.
2	Graduates demonstrate an ability to identify, formulate and solve engineering problems
3	Graduates demonstrate an ability to design and conduct experiments, analyze and interpret data.
4	Graduates demonstrate an ability to design a system, component or process as per needs and specifications
5	Graduates demonstrate skills to use modern engineering tools, software and equipment to analyze for problem solving.
6	Graduates demonstrate an ability to visualize and work on laboratory and multi disciplinary tasks.
7	Graduate shows the understanding of impact of environment and society of engineering solutions and aim to provide sustainable solutions.
8	Graduates demonstrate knowledge of professional and ethical responsibilities.
9	Graduates shall be able to work independently and also in multi disciplinary teams
10	Graduates are able to communicate effectively in both verbal and written form.
11	Graduates will demonstrate the ability to handle the projects through appropriate project management techniques.
12	Graduates develop confidence for self education and ability for life- long learning

PROGRAM EDUCATIONAL OBJECTIVES (PEOs)

The mechanical engineering graduates will

- **PEO1** possess the required foundation and knowledge in the field of mechanical engineering.
- **PEO2** advance professionally as a result of their ability to solve technical problems and work in multidisciplinary teams leading to significant contribution to the industry
- **PEO3** acquire life long learning through training programs and higher qualifications.

PROGRAM SPECIFIC OUTCOMES (PSOs)

- **PSO1** Apply principles of basic sciences and engineering to mechanical systems
- **PSO2** Model, analyze, design, and realize mechanical components and processes
- **PSO3** Be prepared to work professionally and ethically in thermal, design and manufacturing areas of mechanical engineering

VASAVI COLLEGE OF ENGINEERING (AUTONOMOUS) <u>SCHEME OF INSTRUCTION AND EXAMINATION (R-21)</u> <u>B.E. – MECH : SEVENTH SEMESTER (2024-2025)</u>

	B.E (MECH) VII Semester								
		Scheme of Instruction			Scheme of Examination				
Course Code	Name of the Course	H	ours Wee	-	Duration in Hrs	Maximum Marks		Credits	
		L	Т	D/P	in Hrs	SEE	CIE	Č	
	THE	ORY	/			-			
U21PC710ME	Finite Element Analysis	3	-	-	3	60	40	3	
U21PE720ME	Production Drawing	1	-	2	3	60	40	2	
U21PC730ME	Industrial Engineering	3	-	-	3	60	40	3	
U21PE7XXME	Professional Elective – I	3	-	-	3	60	40	3	
U21PE7XXME	Professional Elective – II	3	-	-	3	60	40	3	
U21HS040EH Economics and Finance for Engineers		2	-	-	3	60	40	2	
	PRAC	TICA	LS						
U21PC711ME	Computer Aided Engineering Lab	-	-	2	3	50	30	1	
U21PE7XXME	Professional Elective – I	-	-	2	3	50	30	1	
U21PE7XXME	Professional Elective – II	-	-	2	3	50	30	1	
U21PW719ME	Project Seminar	-	-	2	-	-	30	1	
	TOTAL	15	-	10	-	510	360	20	
GRAND TOTAL 25 870 2							20		
weeks) by th	 Student should complete one NPTEL certification course equivalent to 2 credits (8 weeks) by the end of VII semester. Left over hours allotted to Sports / Library / PDC / Mentor Interaction / CC / RC / TC / 								

	Professional Electives							
		Design engineering Thermal engineering						
		Course Code Title			Title			
	PE-I	U21PE710ME	Robotics	U21PE720ME	Thermal Turbo Machines			
Sem.	PE-II	U21PE730ME	Unmanned Arial Vehicles	U21PE740ME	Computational Fluid Dynamics			
	PE I lab	U21PE711ME	Robotics Lab	U21PE721ME	Thermal Turbo Machines Lab			
	PE II Lab	U21PE731ME	Unmanned Arial Vehicles Lab	U21PE741ME	Computational Fluid Dynamics Lab			

IBRAHIMBAGH, HYDERABAD – 500 031 Department of Mechanical Engineering

FINITE ELEMENT ANALYSIS

SYLLABUS FOR B.E. VII-SEMESTER

L:T:P(Hrs/week): 3:0:0	SEE Marks : 60	Course Code : U21PC710ME
Credits : 3	CIE Marks: 40	Duration of SEE : 3 Hours

The objectives of this course are to: understand the	At the end of the course, students shall be able to:
concept of FEA and apply it to 1-dimensional and 2- dimensional problems of structural analysis and 1- dimensional problems of thermal analysis.	 understand the shape functions and formulate the finite element equations for 1-D elements. evaluate the deflections, stresses and strains for trusses and beams. analyze two dimensional problems for their deflections, stresses and strains. understand the principles used in FE software tools and analyse one dimensional steady state heat transfer problems.
	 formulate the eigen value problem of dynamic systems and obtain the eigen values and eigen vectors for a stepped bar and a beam.

	CO-PO and CO-PSO mapping														
CO		PO mapping PSO mapping													
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	2	2	3	2	3								2	3	1
CO2	1	3	3	1	3								3	2	2
CO3	2	2	2	2	3								2	3	1
CO4	1	3	3	2	2								3	2	2
CO5	2	2	3	1	3								2	3	1

UNIT-I

Introduction to Finite Element Method, stress and Equilibrium, Strain, displacement, stress– strain relations.

One dimensional problems:

Methods of Finite Element formulations Potential Energy approach, assembly of Global stiffness matrix and load vector, Finite element equations for one dimensional linear bar element,

UNIT – II : Analysis of trusses and beams:

Element stiffness matrix for a plane truss member. Analysis of plane trusses, element stiffness matrix for a 2D-beam member (one rotation and one translation at each node), analysis of 2D beams by using point load and UDL.

UNIT – III: Two dimensional problems:

Element stiffness matrix for constant strain triangle element (CST), two dimensional stress analysis using CST elements.

$\mathbf{UNIT} - \mathbf{IV}$

Introduction of Finite Element analysis software: Pre-processing, solution, post processing.

Mesh requirements, type of elements and their degrees of freedom, convergence requirements.

Numerical integration using Gaussian Quadrature with two and three point formulae for one dimensional problem.

Steady state one dimensional conduction heat transfer analysis of composite wall.

UNIT – V

Dynamic Analysis: Formulation of finite element model, properties of eigen vectors, lumped and consistent mass matrices, evaluation of Eigen values and Eigen vectors for a stepped bar and a beam.

Learning Resources:

- 1. Tirupathi R, Chandraputla and Ashok D Belagundu, "Introduction to finite elements in engineering", Prentice Hall of India, 1997.
- 2. G.Ramamurthy, "Applied Finite Element Analysis", I.K. International Publishing House Pvt. Ltd., New Delhi. 2009.
- 3. Rao S S, "The Finite Element Method in Engineering", Pergamon Press, 1989.
- 4. Segerlind L J, "Applied Finite Element Analysis", Wiley Eastern, 1984
- 5. Reddy J N, "An Introduction to Finite Element Method", McGraw– Hill, 1984

- 1 No. of Internal Tests: 02 Max.Marks for each Internal Test: $_{30}$
- 2 No. of Assignments: 03 Max. Marks for each Assignment: 05
- 3 No. of Quizzes: 03 Max. Marks for each Quiz Test: 05 Duration of Internal Test: 90 Minutes

IBRAHIMBAGH, HYDERABAD – 500 031 Department of Mechanical Engineering

PRODUCTION DRAWING

SYLLABUS FOR B.E.VII-SEMESTER

L:T:P(Hrs/week): 1:0:2	SEE Marks:60	Course Code: U21PC720ME
Credits: 02	CIE Marks:40	Duration of SEE: 03Hours

	COURSE OUTCOMES
COURSE OBJECTIVES The objective of this course is to	On completion of the course, students will be able to
practice the conventional representation of machine elements; limits, fits and tolerances; surface finish and surface treatments; make production drawings and process sheets for a given assembly.	 revise the fundamentals of drawing, materials and symbols to implement them later in Production drawings. understand limits, fits and tolerances to indicate them on drawings to get suitable fits after assembly. understand the need for surface roughness between surfaces in contact to select suitable mfg process. prepare the process sheet for various components to show the sequence of mfg processes, machines to be used with work holding details. prepare production drawings for parts of various assemblies indicating all conventions required for manufacturing.

UNIT-I: INTRODUCTION

Need for production drawing, drawing sheet layout, title block, code designation of steels, copper and Aluminum alloys, Conventional representation of materials and machine components, welding symbols, hydraulic and pneumatic symbols, drafting abbreviations and surface treatment symbols.

UNIT-II: LIMITS, TOLERANCES AND FITS

Limit systems, Tolerances, Fits, Tolerances of form and position- and their indication on a drawing, material condition(MMC and LMC), Geometrical tolerancing for MMC.

UNIT-III: SURFACE ROUGHNESS

Surface Roughness, surface roughness number, surface roughness expected from manufacturing processes, indication of surface roughness, special surface roughness characteristics, direction of lay, indication of surface roughness symbols on drawings.

UNIT-IV: PROCESS SHEET

Process sheet, its details and uses, process sheet for various machine components like tenon, bearing brass, slip bush, helical gear, flange, main spindle etc.

UNIT-V: PRODUCTION DRAWING

Production drawings from assembly drawings indicating conventions of flange coupling, Universal coupling, foot-step bearing, eccentric, stuffing box, hydraulic cylinder, petrol engine connecting rod, cross head, piston and screw jack.

N.B.: Tolerance charts to be provided in the examination hall for calculation of limits.

Learning Resources:

1. K.L. Narayana, P. Kannaiah and K. Venkata Reddy, "Production Drawing", New Age International Pvt. Ltd., Revised Ed. 1997.

2. T. Narasimha Reddy, T. A. Janardhan Reddy and C. Srinivasa Rao, "Production Drawing Practice", Hitech Publishers, 2001.

3. R.K. Jain, "Engineering Metrology", Khanna Publishers, 2009.

- 1 No. of Internal Tests: 02
- 02 Max. Marks for each Internal Test: 30
- 2 No. of Assignments:
- 03 Max. Marks for each Assignment: 05
- 3 No. of Quizzes:
- 03 Max. Marks for each Quiz Test: 05

IBRAHIMBAGH, HYDERABAD – 500 031 Department of Mechanical Engineering

INDUSTRIAL ENGINEERING

SYLLABUS FOR B.E.VII-SEMESTER

L:T:P(Hrs/week): 3:0:0	SEE Marks:60	Course Code: U21PC730ME
Credits: 03	CIE Marks:40	Duration of SEE: 03Hours

COURSE OBJECTIVES The objective of this course is to	COURSE OUTCOMES On completion of the course, students will be able to
The objectives of this course are to: study work environment, cost analysis, mathematical models to practical problems, inventory control and project management.	 cost estimation and best suitable person for the given job. Formation of mathematical model to solve practical problems determine the optimal maintenance of inventory to minimise the total cost using different inventory models. construct network models to estimate the project completion time using PERT and CPM techniques.

Unit-I

Work Study: Definition of work study and method study, objectives of method study, method study procedure, various charts for recording. Definition of work measurement, objectives, procedure, stop watch time study, work sampling, standard time calculations, Principles of motion economy.

Unit-II

Job evaluation Definition, objectives various methods of job evaluation . merit rating definition, objectives and various methods of rating, Elements of Cost, overheads, determination of selling price of a product, Break even analysis.

Unit-III

LPP: Formation of LPP, solution to LPP graphical and simplex method, big M method, special cases in LPP, Transportation and assignment models.

Unit-IV

Inventory Control: Importance of inventory control, types of inventory models, inventory costs deterministic inventory models – basic EOQ model derivation, production model without shortages, purchase model with instantaneous replenishment and with shortages, production model with shortages, inventory model with price breaks, fixed order quality system, periodic review system, ABC and VED analysis, problems on ABC analysis.

Unit-V

Project Management: Network fundamentals, differences between PERT and CPM, scheduling the activities, Fulkerson's rule, Earliest and Latest times, determination of ES and EF in forward path, LS & LF in backward path, determination of critical path, Free float, independent float, Total float, program evaluation and review technique, crashing of network.

Learning Resources:

- 1. Joseph Monk," Operations Management", TMH Publishers, New Delhi, 2004
- 2. Buffa Elwood S," Modern Production / Operations Management", John Wiley Publishers, Singapore, 2002
- 3. Everett, E. Adam. Jr and Ronald. J. Ebert, "Production and operations management: concepts, models and behaviour" Prentice Hall of India Pvt. Ltd., New Delhi, 5th ed. 1998.
- 4. S.D. Sharma, "Operations Research", Kedarnnath, Ramnath& Co., Meerut, 2009.
- 5. R.M.Barnes: An introduction to method study and work measurement.

- 1 No. of Internal Tests: 02 Max. Marks for each Internal Test: 30
- 2 No. of Assignments: 03
- 3 Max. Marks for each Assignment: 05
- 3 No. of Quizzes: 03 Max. Marks for each Quiz Test: 05

IBRAHIMBAGH, HYDERABAD – 500 031 Department of Mechanical Engineering

ROBOTIC ENGINEERING (PE-I)

SYLLABUS FOR B.E.VII-SEMESTER

L:T:P(Hrs/week): 3:0:0	SEE Marks:60	Course Code: U21PE710ME
Credits: 03	CIE Marks:40	Duration of SEE: 03Hours

COURSE OBJECTIVE	COURSE OUTCOMES
The objective of the	On completion of the course, students will be able to
course is to	
study robot anatomy, configuration, sensors, drives and applications of robots; forward & inverse kinematics, dynamics and control.	 explain basic terminology of robotics and summarize various industrial applications and specifications of robots. apply direct and inverse kinematics to different robot manipulators using principles of D-H transformation. utilize Jacobian matrix for velocity relationship of joints and end effector and plan trajectory of robots using different techniques. estimate robot dynamics using Lagrange and Newton- Euler methods and develop control laws. outline different types of end effectors, sensors and drives that are needed for effective working of robots.

	CO-PO and CO-PSO mapping															
CO		PO mapping												PSO mapping		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3	
CO1	3						2						2		2	
CO2	3	3			2						1		3	1	2	
CO3	3	3			2								3	1	2	
CO4	3	3			2						1		3	3	1	
CO5	3						2						2	1	2	

UNIT-I

Laws of robotics, Basic terminology, Basic configurations, Degrees of freedom, work envelope, motion control methods. Applications in industry – material handling, loading & unloading, processing, welding & painting applications, assembly and inspection, Robot specification requirements.

UNIT-II

Rotation matrix. Euler angles. RPY representation, Homogeneous transformation matrix. Denavit – Hartenberg convention. Direct and inverse kinematics for industrial robots for position and orientation.

UNIT-III

Manipulator Jacobian. Joint–End effector velocity, Direct and inverse velocity analysis, Trajectory planning, Static force and moment transformation, Singularities, Redundancy.

UNIT-IV

Robot dynamics: Lagrangian and Newton–Euler formulation for RR & RP manipulators.

UNIT-V

3

End effectors: classification and working principle.

Sensors: Position, velocity, vision, proximity and range, tactile and force. Drives for robots: Electrical, hydraulic and pneumatic.

Learning Resources:

- 1. M.W.Spong and M.Vidyasagar, "Robot Dynamics and Control", 1st Edition, John Wiley and sons, 1990.
- 2. R.K.Mittal and I.J.Nagrath, "Robotics and Control", Tata McGraw-Hill, 2003.
- 3. Mikell P. Groover, Mitchell Weiss, Roger N. Nagel and Nicholas G. Odrey, "Industrial Robotics: Technology, Programming and Applications", McGraw-Hill Companies, 1986.
- 4. H.Asada and J-J.E.Slotine, "Robot Analysis and Control", Wiley Interscience, 1986.
- 5. K.S. Fu,R.C.Gonzalez and C.S.G. Lee , "Robotics, Control Sensing Vision and Intelligence", McGraw Hill, Int. Ed. 1987.
- 6. Siciliano, Bruno, Lorenzo Sciavicco, Luigi Villani, and Giuseppe Oriolo. Robotics: modelling, planning and control. Springer Science & Business Media, 2010.

- 1 No. of Internal Tests: 02 Max.Marks for each Internal Test: 30
- 2 No. of Assignments: 03 Max. Marks for each Assignment: 05
 - No. of Quizzes: 03 Max. Marks for each Quiz Test: 05
 - Duration of Internal Test: 90 Minutes

IBRAHIMBAGH, HYDERABAD – 500 031 Department of Mechanical Engineering THERMAL TURBO MACHINES (PE-I)

SYLLABUS FOR B.E.VII-SEMESTER

L:T:P(Hrs/week): 3:0:0	SEE Marks:60	Course Code: U21PE720ME
Credits: 03	CIE Marks:40	Duration of SEE: 03Hours

COURSE OBJECTIVE The objective of the course is to	COURSE OUTCOMES On completion of the course, students will be able to							
Understand basics of	 evaluate the basic properties of							
compressible flows, study basic	compressible flow. analyze the performance of centrifugal							
principles, governing equations	and axial flow compressors. explain the working principle of steam							
and analysis of flow through	turbines and analyze their performance. estimate the performance of various gas							
turbo machines, jet and rocket	turbine cycles. illustrate the working of jet and rocket							
propulsion systems.	propulsion systems.							

	CO-PO and CO-PSO mapping															
CO		PO mapping												SO mapping		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3	
CO1	2	2	1	1	1							1	3	2	2	
CO2	3	2	2	2	1							1	3	2	2	
CO3	3	2	2	2	1							1	3	2	2	
CO4	3	2	2	2	1							1	3	2	2	
CO5	3	2	1	2	1							1	3	2	2	

UNIT-I: COMPRESSIBLE FLOWS

Speed of pressure waves, Mach number, acoustic velocity, Mach cone and Mach angle; static and stagnation properties; Stagnation enthalpy, stagnation temperature, stagnation pressure, stagnation velocity of sound and stagnation density, various regions of flow, aerofoil nomenclature, lift and drag.

UNIT-II: ROTO DYNAMIC COMPRESSORS

Classification, Centrifugal compressors: principle of operation, Euler Equation, velocity triangles, pre-whirl, slip factor work done. Axial flow compressors: working principle, velocity triangles, Work done factor, stage efficiency, degree of reaction, chocking, surging and stalling.

UNIT-III: STEAM TURBINES

Classification; Impulse turbine - nozzle efficiency, blade efficiency, gross and stage efficiencies; velocity triangles, optimum blade speed ratio, maximum work done and blade efficiency; Compounding of steam turbines.

Reaction turbine- velocity triangles, degree of reaction, blade efficiency, maximum work done.

UNIT-IV: GAS TURBINES

Classification and applications; constant pressure gas turbines, Joule cycleconfiguration diagram and T-s diagram, thermal efficiency, maximum pressure ratio, optimum pressure ratio for maximum work done, inter-cooling, reheating and regeneration.

UNIT-V: JET AND ROCKET PROPULSION

Introduction, jet engine types and applications, air craft propulsion theory, thrust, thrust power and propulsive efficiency; Turbo jet, Turbo prop, Turbo fan engines, Ramjet engines, pulse jet engines, thrust augmentation;

Rocket Propulsion: types of propellants and working of Rocket engines, Rocket propulsion theory and applications.

Learning Resources:

- 1. Yahya S.M. "Fundamentals of compressible flow", New Age International publishers, January 2016.
- 2. Yadav R. "Steam and Gas Turbines and Power plant Engineering", Central Publishing House Ltd, Allahabad.
- 3. Rajput R.K. "Thermal engineering", Laxmi publications Pvt. Ltd.," 10th edition
- 4. Ganesan, V., "Gas Turbines", Tata McGraw Hill Book Company, New Delhi.
- 5. Cohen H Rogers and G.F.C. and H.I.H. Saravanamuttoo, "Gas Turbine Theory", Longman, 5th Edition, New York.

1	No. of Internal Tests:	02	Max. Marks for each Internal Test:	30
2	No. of Assignments:	03	Max. Marks for each Assignment:	05
3	No. of Quizzes:	03	Max. Marks for each Quiz Test:	05
	Duration of Internal Test:	90 Mir	nutes	

IBRAHIMBAGH, HYDERABAD – 500 031 Department of Mechanical Engineering

UNMANNED AERIAL VEHICLES (PE-II)

SYLLABUS FOR B.E.VII-SEMESTER

L:T:P(Hrs/week): 3:0:0	SEE Marks:60	Course Code: U21PE730ME
Credits: 03	CIE Marks:40	Duration of SEE: 03Hours

Course objectives	Course Outcomes
The objective of this Course is to understand the features of UAV, elements, navigation and guidance of UAV and to design and simulate UAV	 After successfully completing the course students will be ableto: explain the types and characteristics of UAVs and their applications. illustrate the concepts of aerodynamics of flight vehicle. identify and explain the components, sensors and payload of UAVs, their navigation and guidance. design and perform design, simulation and structural analysis of UAV components. design and perform aerodynamic analysis of UAV components

	CO-PO and CO-PSO mapping														
CO		PO mapping PSO mapping												oing	
	1	1 2 3 4 5 6 7 8 9 10 11 12 1 2 3													
CO1	3	2				3	3	3				3	3	2	3
CO2	3	3				ŝ	3	2				3	3	2	3
CO3	3	2				3	3	2				3	3	2	3
CO4	3	2				3	3	2				3	3	2	3
CO5	3	2				3	3	2				3	3	2	3

UNIT-I Introduction to UAV:

UAV: Definition, History; Difference between aircraft and UAV; DGCA Classification of UAVs; Types and Characteristics of Drones: Fixed, Multi-rotor, and Flapping Wing; Applications: Defense, Civil, Environmental monitoring.

UNIT-II Basics of Flight:

Different types of flight vehicles; Components and functions of an airplane; Forces acting on Airplane; Physical properties and structure of the atmosphere; Aerodynamics – aerofoil nomenclature, aerofoil characteristics, Angle of attack, Mach number, Lift and Drag, Propulsion and airplane structures.

UNIT-III UAV Elements, Navigation and Guidance:

Components: Arms, motors, propellers, electronic speed controller (ESC), flight controller; Propulsion; Data Link; Sensors and Payloads: GPS, IMU, Light Detection and Ranging (LiDAR), Imaging cameras, Classification of payload based on applications; Hyper-spectral sensors; Laser Detection and Range (LADAR); Synthetic Aperture Radar (SAR); Thermal cameras; ultra-sonic detectors; Case study on payloads. Introduction to navigation systems and types of guidance; Mission Planning and Control.

UNIT-IV

Design & Simulation of UAV:

Introduction to CAD; Design of UAV components; Structural Analysis using CAE; Manufacturing of the components of UAVs: 3D printing; Case studies – Design of nanosize (hand held) multirotor UAV, design of landing gear for multirotor

UNIT-V

Aerodynamic analysis: Introduction to Modeling and CFD analysis of UAV, Multirotor Aerodynamic Interaction and Investigation, CFD Analysis – Multi rotor, Fixed Wing for materials carbon fiber, glass fiber; case study- Small Scale UAV wing design and CFD analysis to obtain maximum efficiency, Aerodynamic and stability analysis of VTOL.

Learning Resources:

- 1. Handbook of unmanned aerial vehicles, K Valavanis; George J Vachtsevanos, New York, Springer, Boston, Massachusetts : Credo Reference, 2014. 2016.
- 2. Building Your Own Drones: A Beginners' Guide to Drones, UAVs, and ROVs, John Baichtal
- 3. DGCA RPAS Guidance Manual, Revision 3 2020

The break-up of CIE: Internal Tests + Assignments + Quizzes

No. of Internal Tests: Max. Marks for each Internal Test: 30 02 1 2 No. of Assignments: 03 Max. Marks for each Assignment: 05 3 No. of Quizzes: 03 Max. Marks for each Quiz Test: 05 Duration of Internal Test: 90 Minutes

IBRAHIMBAGH, HYDERABAD – 500 031 Department of Mechanical Engineering

Computational Fluid Dynamics (PE-II)

SYLLABUS FOR B.E.VII-SEMESTER

L:T:P(Hrs/week): 3:0:0	SEE Marks:60	Course Code: U21PE740ME
Credits: 03	CIE Marks:40	Duration of SEE: 03Hours

Course objectives	Course Out comes
The objectives of this course are to: 1. equip the students with the	After completing the course, the student will be able to:
necessary governing equations to use computational techniques to solve problems related to fluid flow and heat transfer.	 familiarize with the differential equations for fluid flow & heat transfer and apply numerical methods for their solution find solution of partial differential equations to estimate the behaviour of the flow
 provide the essential numerical background for solving the partial differential equations governing the fluid flow and heat transfer 	 phenomena. develop flow simulation code for heat transfer and fluid flow applications using FDM and FVM. make use of different iterative methods to solve algebraic equations for Heat transfer
	and fluid flows 5. apply suitable grid generation methods to decompose the fluid /solid domain for obtaining the numerical solution

	CO-PO and CO-PSO mapping															
CO		PO mapping												PSO mapping		
	1	1 2 3 4 5 6 7 8 9 10 11 12 1 2 3														
CO1	3	2	2	2	2	1							1	2	1	
CO2	3	2	2	2	2	1							1	2	1	
CO3	3	2	2	2	2	1							1	2	1	
CO4	3	2	2	2	2	1							1	2	1	
CO5	3	1	2	2	2	1							1	2	1	

UNIT – I

Introduction to computational Fluid flows, CFF applications, comparison amongst Numerical, Analytical and Experimental approaches.

Review of the basic fluid dynamics: Continuity, Navier Stokes equations, Reynolds and Favre averaged N– S equations. Heat transfer conduction

equation for steady and unsteady flows, steady convection- diffusion equation.

Unit– II

Classification of partial differential equations – Elliptic, parabolic and hyperbolic equations. Practical examples of elliptic, parabolic and hyperbolic partial differential equations, Well posed problem; Initial and boundary value problems.

Turbulence - Introduction, Mixing length model, K– epsilon turbulence model.

Unit– III

Concepts of Finite difference methods– forward, backward and central difference. Finite difference solution– 1-D steady state heat conduction without and with constant source term; parabolic partial differential equations– Euler, Implicit method, Crank Nicolson method.

Errors, Consistency, Stability analysis, Convergence criteria

Unit– IV

Solution of System of Linear Algebraic Equations: Tridiagonal matrix algorithm (TDMA): Iteration methods: Jacobi and Gauss-Seidel.

Viscous incompressible flow, stream function– Vorticity method.

Introduction to grid generation– Types of grid –Structured and Unstructured grids.

Unit– V

Introduction to finite volume method: Finite volume formulations for diffusion equation, 1-D steady state heat conduction without and with constant source term;

Convection diffusion equation: Central difference scheme, Upwind scheme, Staggered grid, SIMPLE Algorithm.

Learning Resources:

- 1. John D Anderson, "Computational Fluid Dynamics", Mc Graw Hill Inc., New York, 2003.
- 2. Patankar S V, "Numerical Heat Transfer and Fluid Flow", Hemisphere Publishing Company, New York 1980.
- 3. H.K. Versteeg, W. Malalasekara, "An Introduction to computational Fluid Dynamics", 2nd Ed., Pearson Education, 2007.
- 4. Chung T J, "Computational Fluid Dynamics", Cambridge University Press, New York, 2002
- 5. Muralidhar K, Sundararajan T, "Computational Fluid Flow and Heat Transfer", Narosa publication House, New Delhi, 2003.

1	No. of Internal Tests:	02	Max. Marks for each Internal Test:	30
2	No. of Assignments:	03	Max. Marks for each Assignment:	05
3	No. of Quizzes:	03	Max. Marks for each Quiz Test:	05
	Duration of Internal Test:	90 Mir	nutes	

IBRAHIMBAGH, HYDERABAD – 500 031

Department of Humanities and Social Sciences

ECONOMICS AND FINANCE FOR ENGINEERS

SYLLABUS FOR B.E.VII-SEMESTER

L:T:P(Hrs/week): 2:0:0	SEE Marks:60	Course Code: U21HS040EH
Credits : 02	CIE Marks:40	Duration of SEE: 03Hours

Course objectives The objective of this course is to	Course Outcomes On completion of the course, students will be able to
understand the concepts and tools of economics, cost and finance that will equip them for decision making.	 gain a conceptual understanding economics as a discipline. construct a cost sheet and classify costs and make use of break-even analysis in decision making. evaluate the accounting cycle and explain its importance in recording business transactions. Analyze the financial position of business a firm through calculation and interpretation of ratios. Compare and evaluate Long term investment decisions in business

Unit I: Concepts in Economics

Definition of Managerial Economics- Scope of Managerial Economics -Relevance of Economics for Engineers- Law of Demand- assumptions and exceptions - Price elasticity of demand (Application-oriented approach)

Unit II: Cost Analysis and Profit Planning

Concept of Cost - Classification of Costs (Fixed Vs Variable, Implicit Vs Explicit, Incremental Vs Marginal)–Preparation of Cost Sheet (Simple Problems)– Breakeven Analysis (Application-oriented approach)

Unit III: Conceptual Understanding of Accounting

Accounting Cycle-Journal-Subsidiary Books- Ledger-Trial Balance-Final Accounts (Trading, Profit and Loss Account, Balance Sheet (Theory Only) Preparation of Trading and Profit and Loss Account and Balance Sheet (Problems without adjustments)

UNIT IV: Financial Statement Analysis

Ratio Analysis-uses and limitations- Liquidity, Solvency, Activity & Profitability Ratios (simple problems)

Unit V: Long Term Investment decisions:

Capital Budgeting –Traditional and DCF Techniques (simple problems)

Learning Resources:

- 1. S.P.Jain and K.L Narang., "Financial Accounting", Kalyani Publishers Latest edition.
- 2. S.P.Jain and K.LNarang., "Cost Accounting", Kalyani Publishers, Latest edition.
- 3. M.Y.Khan and P.K. Jain., "Financial Management Text, Problems and Cases", Mc Graw Hill Education Private Limited, New Delhi. Latest edition
- 4. M. Kasi Reddy &Saraswathi, Managerial Economics and Financial Analysis, PHI New Delhi, Latest edition.

Reference books:

- 1. Mehta P.L., "Managerial Economics: Analysis, Problems and Cases", Sultan Chand and Sons. Latest edition.
- 2. Narayanaswamy, "Financial Accounting: A Managerial Perspective", Prentice Hall India
- 3. M. L. Seth., "Micro Economics", Lakshmi Narain Agarwal. Latest edition
- 4. Dr. R.P. Rustagi., "Fundamentals of Financial Management" Taxmann Publications. Latest Edition

1	No. of Internal Tests:	02	Max. Marks for each Internal Test:	30
2	No. of Assignments:	03	Max. Marks for each Assignment:	05
3	No. of Quizzes:	03	Max. Marks for each Quiz Test:	05
	Duration of Internal Test:	90 Min	nutes	

IBRAHIMBAGH, HYDERABAD – 500 031 Department of Mechanical Engineering

COMPUTER AIDED ENGINEERING LAB

SYLLABUS FOR B.E.VII-SEMESTER

L:T:P(Hrs/week): 0:0:2	SEE Marks:50	Course Code: U21PC711ME				
Credits: 01	CIE Marks:30	Duration of SEE: 03Hours				

COURSE OBJECTIVE The objective of the course is to	COURSE OUTCOMES On completion of the course, students will be able to
understand the CAE software applicability for analyzing structural and thermal problems and correlate mathematical formulation using FE method.	 select appropriate finite element and solve1-D, 2-D and 3-Dstatic structural problems. Perform Modal, Harmonic and Transient analysis on beams. select appropriate finite element and solve 1-D,2-D thermal problems. understand the importing of complex models from modelling software and perform analysis using FE software.

	CO-PO and CO-PSO mapping														
CO	PO mapping											PSC) mapp	ing	
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	1	2	2	3	2								2	2	3
CO2	2	3	2	3	3								2	3	2
CO3	1	2	3	ŝ	2								1	2	3
CO4	1	2	2	3	3								2	3	2

List of Experiments

- 1. Introduction to FEA software. Analysis using 1-d bar elements.
- 2. Analysis of Trusses
- 3. Analysis of Beams with different boundary conditions
- 4. Analysis of Beams with different loading conditions
- 5. Analysis of Plane stress and Plane strain problems
- 6. Analysis of axi-symmetric problems
- 7. Analysis of three dimensional objects by modeling them in FEA software
- 8. Modal Analysis of Beams.
- 9. Harmonic Analysis of Beams

- 10. Transient Analysis of Beams
- 11. Steady state Heat Transfer Analysis of a composite wall and a Fin
- 12. Developing a 3-D Model in a modeling software and analyzing it by importing into FEA software
- 13. Buckling analysis of columns.
- 14. Dynamic analysis of mechanisms

From the above experiments, each student should perform at least 12 (Twelve) experiments.

No. of Internal Tests:	02	Max. Marks for Internal Tests:	12		
Marks for day-to-day laboratory class work					
Duration of Internal Test: 2 Hours					

IBRAHIMBAGH, HYDERABAD – 500 031 Department of Mechanical Engineering

ROBOTIC ENGINEERING LAB

SYLLABUS FOR B.E. VII-SEMESTER

Instruction : 2 Hours /week	SEE Marks	: 50	Course Code :	U21PE711ME
Credits : 1	CIE Marks:	: 30	Duration of SEE	: 2 Hours

COURSE OBJECTIVE	COURSE OUTCOMES					
The objective of the course is	On completion of the course, students will be able					
to	to					
model, analyses different types of industrial robotics using CAD software and 6DOF serial manipulator.	 Modelling of various industrial robotics using ADAMS software. Designing and controlling of robotic path using various sensors. Analyses of forward and inverse kinematics of industrial manipulator using 6-dof serial manipulator 					

	CO-PO and CO-PSO mapping													
CO	PO mapping PSO mapping													
	1	1 2 3 4 5 6 7 8 9 10 11 12 1 2 3						3						
CO1	1	3		1	3						2	1	3	2
CO2	1		3	1	3						2	1	3	2
CO3	1	3		1	3						2	1	3	2

List of Experiments:

- 1. Modelling of 6 DOF anthropomorphic arm in ADAMS.
- 2. Simulation of 6 DOF anthropomorphic arm in ADAMS.
- 3. Forward kinematic analysis of industrial manipulator using MATLAB
- 4. Inverse kinematic analysis of industrial manipulator using MATLAB
- 5. Assembling of robot mechanical components mounting of motors, sensors, electronic circuits to the chassis
- 6. Forward kinematic analysis of 6-DOF serial manipulator
- 7. Inverse kinematic analysis of 6-DOF serial manipulator
- 8. Demonstration on navigation and obstacle avoidance robot using ultrasonic sensor
- 9. Simulation of industrial manipulator using Coppeliasim.
- 10. Demonstration on unmanned aerial vehicles.

No. of Internal Tests:	01	Max. Marks for Internal Test:	12		
Marks for day-to-day laboratory class work 18					
Duration of Internal Test: 3Hours					

IBRAHIMBAGH, HYDERABAD – 500 031 Department of Mechanical Engineering

THERMAL TURBO MACHINES LAB (PE-I Lab)

SYLLABUS FOR B.E.VII-SEMESTER

L:T:P(Hrs/week): 0:0:2	SEE Marks:50	Course Code: U21PE721ME				
Credits: 01	CIE Marks:30	Duration of SEE: 03Hours				

COURSE OBJECTIVE	COURSE OUTCOMES					
The objective of the course	On completion of the course, students will be able to					
is to						
apply basic laws of thermodynamics and heat transfer to thermal systems, principles of turbomachinery to fluid systems.	 study the various modes of heat transfer using heat transfer equipment. determine the COP of air conditioning/refrigeration system. study the pressure distribution on various aerodynamic models and calculate lift and drag coefficients using low speed wind tunnel. evaluate the performance of thermal turbomachines 					
	(centrifugal blower and axial fan).					

	CO-PO and CO-PSO mapping														
CO		PO mapping PSO mapping													oing
	1	1 2 3 4 5 6 7 8 9 10 11 12 1 2 3												3	
CO1	3	2	3	1						2		1	3	1	2
CO2	3	2	3	1						2		1	3	1	2
CO3	3	3 2 3 1 2 1 3 1 2										2			
CO4	3	3 2 3 1 2 1 3 1 2												2	

List of Experiments

- 1. Determination of thermal conductivity of insulating material using Lagged pipe apparatus.
- 2. Determination of heat transfer coefficient under natural convection
- 3. Determination of pin–fin efficiency subjected to natural and forced convection.
- 4. Determination of effectiveness of parallel flow and counter flow heat exchanger.
- 5. Determination of emissivity of a plate.
- 6. Determination of Stefan Boltzmann constant.
- 7. Determination of COP of the Refrigeration systems using capillary tube.
- 8. Pressure distribution on symmetrical and unsymmetrical specimen in wind tunnel.
- 9. Measurement of lift and drag forces of the model in wind tunnel.
- 10. To study of performance characteristics curves of a centrifugal blower.
- 11. To study of performance characteristic curves of an axial flow fan.

- 12. Determination of CoP of air conditioning test rig.
- 13. Study the gas turbine model.

No. of Internal Tests:	02	Max. Marks for Internal Tests:	12					
Marks for day-to-day laboratory class work								
Duration of Internal Test: 2Hours								

IBRAHIMBAGH, HYDERABAD – 500 031 Department of Mechanical Engineering

UNMANNED AERIAL VEHICLES LAB (PE-II Lab)

SYLLABUS FOR B.E.VII-SEMESTER

L:T:P(Hrs/week): 0:0:2	SEE Marks:50	Course Code: U21PE731ME
Credits : 01	CIE Marks:30	Duration of SEE: 03Hours

List of Experiments

- 1. To determine the effect of angle of attack on the lift and drag of unsymmetric wing profile of fixed wing UAV.
- 2. To determine the effect of velocity on the lift and drag of unsymmetric wing profile of fixed wing UAV.
- 3. To determine the effect of pressure variation on the symmetric wing profile of the fixed wing UAV
- 4. To develop propeller blade profile using CAD software.
- 5. To develop wings profile using CAD software.
- 6. Creation of simple surfaces using revolved surface, ruled surface, 3D surface command.
- 7. To design solid primitives by using region extrude and revolved features.
- 8. Creating explode views of drone components assembly using CAD software.
- 9. To perform the structural analysis of fixed wing and multi rotor UAV using CAD Software
- 10. To perform the structural analysis of multi rotor UAV using CAD Software
- 11. To

assembleUAVmechanicalcomponents, mountingofmotors, sensors, electronic circuits to the frame.

- 12. To design and develop nano size (handheld) multirotor UAV using 3d printing,
- 13. To design and develop landing gear for multirotor UAV using 3d printing.
- 14. To develop small scale UAV wing design and CFD analysis to obtain maximum efficiency,
- 15. To perform Aerodynamic and stability analysis of VTOL for UAV.

No. of Internal Tests:	02	Max. Marks for Internal Tests:	12					
Marks for day-to-day laboratory class work								
Duration of Internal Test: 2Hours								

IBRAHIMBAGH, HYDERABAD – 500 031 Department of Mechanical Engineering

COMPUTATIONAL FULID DYNAMICS LAB (PE-II Lab)

SYLLABUS FOR B.E.VII-SEMESTER

L:T:P(Hrs/week): 0:0:2	SEE Marks:50	Course Code: U21PE741ME
Credits: 01	CIE Marks:30	Duration of SEE: 03Hours

COURSE OBJECTIVE	COURSE OUTCOMES								
The objective of the course is to	On completion of the course, students will be able to								
To study and analyze the internal and external over profiles using commercial software package.	 understanding modelling and meshing of geometries in computational tools analyze internal and external flow using various geometries analyse steady and unsteady flows analyse fluid flow with heat transfer 								

	CO-PO and CO-PSO mapping														
CO	PO mapping												PS	O mapp	oing
	1	1 2 3 4 5 6 7 8 9 10 11 12 1 2 3										3			
CO1	3	2	3	1						2		1	3	1	2
CO2	3	2	3	1						2		1	3	1	2
CO3	3	3 2 3 1 2 1 3 1 7								2					
CO4	3	2	3	1						2		1	3	1	2

List of Experiments

- 1. Introduction to computational process and computational software package
- 2. Modelling and meshing of basic geometries in workbench
- 3. Develop the numerical solution to a laminar pipe flow.
- 4. Develop the numerical solution to a turbulent pipe flow.
- 5. Develop the numerical solution to a flat plate boundary layer.
- 6. Numerical analysis of compressible flow through a nozzle
- 7. Numerical analysis of flow over an aerofoil
- 8. Analysis of flow through pipe under laminar convection
- 9. Analysis of flow through pipe under turbulent convection
- 10. Analysis of shall and tube heat exchanger
- 11. Steady flow analysis of 3D Bifurcating Artery
- 12. Unsteady flow analysis of 3D Bifurcating Artery

With effect from the Academic Year 2024-25

No. of Internal Tests:	02	Max. Marks for Internal Tests:	12					
Marks for day-to-day laboratory class work								
Duration of Internal Test: 2Hours	5							

IBRAHIMBAGH, HYDERABAD – 500 031 Department of Mechanical Engineering

PROJECT SEMINAR

SYLLABUS FOR B.E.VII-SEMESTER

L:T:P(Hrs/week): 0:0:2	SEE Marks:	Course Code: U21PW719ME
Credits: 01	CIE Marks:30	Duration of SEE:

COURSE OBJECTIVE The objective of the course is to	COURSE OUTCOME On completion of the course, students will be able to
actively involve the students in the initial work required to undertake the final year project.	 do the literature search to identify the project. define the problem and identify the specifications understand tools and techniques to be used in the project design, manufacturing and analysis of the chosen project.

	CO-PO and CO-PSO mapping														
CO		PO mapping) mapp	oing
	1	1 2 3 4 5 6 7 8 9 10 11 12 1 2 3											3		
CO1	3											3	1	1	1
CO2		3	2	2	2							2	2	2	3
CO3												3	2		
CO4	3	3	2	2				3	2	3	2	3	3	1	3

The objective of the project seminar is to actively involve the students in the initial work required to undertake the final year project. It may comprise of:

- 1. Problem definition and specifications.
- 2. A broad understanding of the available techniques to solve a problem of interest.
- 3. Presentation (oral and written) of the project.
- 4. Submission of brief report.

The Department can initiate the work related to project allotment at the end of III year II semester and complete it in the first two weeks of the fourth year I semester.

With effect from the Academic Year 2024-25

First 4 weeks of IV year Ist semester will be spent on special lectures by faculty members, research scholar and speakers from industries and R&D institutions. The objective of these talks is to expose students to real life / practical problems and methodologies to solve them.

A seminar schedule will be prepared by the coordinator for all the students. It should be from the 5^{th} week to the last week of the semester and should be strictly adhered to.

Each student will be required to

- 1. Submit a one page synopsis of the seminar to be delivered.
- 2. Give a 20 minute presentation followed by 10 minutes discussion.
- 3. Submit a technical write up on the talk delivered.

At least two teachers will be associated with the evaluation of the project seminar for the award of the sessional marks which should be on the basis of performance of all the three items stated above.

No. of Presentations	1	Max. Marks for presentation:	30		
Marks will be awarded based on synopsis, submission of write-up and presentation using rubrics.					
Duration of Presentation: 20 min					

VASAVI COLLEGE OF ENGINEERING (AUTONOMOUS) <u>SCHEME OF INSTRUCTION AND EXAMINATION (R-21)</u> <u>B.E. – MECH : EIGHTH SEMESTER (2024-2025)</u>

B.E (MECH) VIII Semester								
		Scheme of Instruction Hours per Week			Scheme of Examination			
Course Code	Name of the Course				Duration	Maximum Marks		dits
		L	т	D/P	in Hrs	SEE	CIE	Credits
THEORY								
U21PE8XXME	Professional Elective-III	3	-	-	3	60	40	3
U21PE8XXME	Professional Elective-IV	3	-	-	3	60	40	3
U21PW819ME	Project / Internship	-	-	12	Viva - Voce	50	50	6
	TOTAL	6	-	12		170	130	12
	GRAND TOTAL	18			300		12	
						-		

Professional Electives								
		Design engineering		Therma	ll engineering	Industrial engineering		
		Course Code	Title	Course Code	Title	Course Code	Title	
II Ser	PE-III		Product Design and Development		Renewable Energy Systems		Supply Chain Management	
	PE-IV		Composite Materials		Power Plant Engineering		Production and Operations Management	

IBRAHIMBAGH, HYDERABAD - 500 031

Department of Mechanical Engineering

PRODUCT DESIGN AND DEVELOPMENT (PE-III)

SYLLABUS FOR B.E.VIII-SEMESTER

L:T:P(Hrs/week): 3:0:0	SEE Marks:60	Course Code: U21PE810ME
Credits: 03	CIE Marks:40	Duration of SEE: 03Hours

COURSE OBJECTIVE	COURSE OUTCOMES						
The objective of the	On completion of the course, students will be able to						
course is to							
Study product and process design	1 illustrate creativity and study the techniques of innovation						
functions, selection and evaluation of	2 assess the evaluation techniques for screening ideas						
projects, new product development, new	3 differentiate the IPR-Patents, Design patents, copy right and trade mark and their laws.						
product planning and product life cycle	4 describe the interaction between design, manufacture, quality, testing and introducing						
management.	new products.Learn new concepts in product development and life cycle management.						

	CO-PO and CO-PSO mapping														
CO		PO mapping											PSC) mapp	ing
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	2	2 1 2 1 2 1 2									1	2	2		
CO2	2		1			2	1	2		1	2		1	2	2
CO3	2		1			2	1	2		1	2		1	2	2
CO4	2	2 1 2 1 2 1 2 1 2 2													
CO5	2		1			2	1	2		1	2		1	2	2

UNIT – I

Product Design and Process Design functions. Selection of right product. Systematic procedure of product innovation. Factors contributing to successful technological innovation – need for creativity and innovation. Techniques of innovation like brain storming and Delphi techniques.

UNIT – II

Project selection and evaluation: Collection of ideas and purpose of project. Selection criteria – screening ideas for new products using evaluation techniques. Principles of ergonomics, function of design – Design with Human Machine Interaction (HMI).

UNIT – III

New Product Development: Concept testing and market analysis.

Intellectual Property Rights (IPR): Types, definitions, Patents, patent search, patent laws, international code for patents

UNIT – IV

New Product Planning: Design principles, design for manufacturing and assembly, quality control during design, prototyping. Steps for introducing new products after evaluation.

UNIT – V

Value engineering: Types of value, functions, value analysis job plan, value analysis tests, costs reduction through VE.

Product life cycle management: Definition, PLM Life cycle model, elements of PLM, need for PLM, opportunities and benefits of PLM, components and phases of PLM, PLM feasibility study, PLM visioning.

Learning Resources:

- 1. Karl T. Ulrich, Steven D. Eppinger, Maria C. Yang, Product Design and Development, Mc Graw Hill 2020.
- 2. Kevin Otto, Kristin Wood, Product Design, Pearson, 2003.
- 3. Chitale AK & Gupta R.C, Product Design & Manufacturing, Prentice Hall of India, 1997.
- 4. Niebel BW & Draper AB, Production Design & Process Engg., Mc Graw Hill Kogakusha, 1974.
- 5. Harry, B. Waton, New Product Planning, Prentice Hall Inc., 1992.
- 6. Greaves Michael, Product Life Cycle Management Driving the next generation of lean thinking, McGraw Hill, 2006, ISBN 0071452303

The break-up of CIE: Internal Tests+Assignments + Quizzes

1	No. of Internal Tests:	02	Max.Marks for each Internal Test:	30
2	No. of Assignments:	03	Max. Marks for each Assignment:	05
З	No of Ouizzes:	03	May Marks for each Ouiz Test	05

3 No. of Quizzes: 03 Max. Marks for each Quiz Test: 05 Duration of Internal Test: 90 Minutes

IBRAHIMBAGH, HYDERABAD – 500 031 Department of Mechanical Engineering

RENEWABLE ENERGY SYSTEMS (PE-III)

SYLLABUS FOR B.E.VIII-SEMESTER

L:T:P(Hrs/week):3:0:0	SEE Marks:60	Course Code: U21PE820ME
Credits :03	CIE Marks:40	Duration of SEE:03Hours

COURSE	COURSE OUTCOMES
OBJECTIVES	On completion of the course, students will be able to
The objective of this	
course is to	
study the availability and applications of various renewable energy systems like solar energy, wind energy, geothermal energy, ocean thermal energy, tidal and wave energy, fuel cell energy and biomass energy.	 Illustrate the constructional details and working of solar energy conversion devices for various heating and cooling applications. describe the working of different wind and geothermal energy conversion systems used for power generation. Explain the working of ocean thermal, tidal and wave energy power plants for power generation. illustrate the constructional details, working and applications of different fuel cells. discuss the constructional details, working of different types of bio gas plants for domestic cooking and other applications.

	CO-PO and CO-PSO mapping														
CO		PO mapping PSO mapping													
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	3	3 2 2 2 2 2 2 3 2 1													
CO2	ŝ	2	2			2	2	2		2			3	2	1
CO3	З	2	2			2	2	2		2			3	2	1
CO4	З	2 2 2 2 2 2 2 2 3 2 1													
CO5	3	2	2			2	2	2		2			3	2	1

UNIT I

Introduction and classification of Renewable Energy Systems.

Solar Energy: Availability of solar energy, Measurement of sunshine, solar radiation data, estimation of average solar radiation, solar energy selection, selective surfaces, constructional details and working of solar flat plate and evacuated tube collectors, solar heating and cooling; other solar thermal applications. Solar Photo-voltaic cell and its efficiency,

UNIT II

Wind Energy: Wind mills and wind turbine systems; classification of wind machines: horizontal & vertical axis configuration; High and low solidity rotors, elements of wind mills and wind turbine systems; Site selection to establish wind turbine power plants, Aerodynamic models, Rankine Froud Actuator disc model.

UNIT III

Geothermal Energy: Earth as source of heat energy; Nature of Geothermal Fields, Geothermal sources. Hydrothermal sources;

Ocean Thermal Energy: Ocean thermal energy sources,

Tidal Energy: Classification and working of Tidal power plants, Limitations of Tidal energy.

Ocean Wave Energy Technology: Classification of wave energy conversion devices;

UNIT IV

Fuel Cell Energy: Description, classification and operation of fuel cells; major components & general characteristics of fuel cells; working of Alkaline Fuel Cell, Direct Methanol Fuel Cell, Phosphoric Acid Fuel Cell, Solid Oxide Fuel Cell, Proton/Polymer exchange membrane fuel cell and molten carbonate fuel cell systems.

UNIT V

Bio-mass Energy: conversion techniques for the production of liquid and gaseous fuels by bio-chemical methods - types of feed stock, constructional details and working of fixed dome, flexible bag and floating dome type bio gas plants,

Learning Resources:

- 1. Twidell J.W. & Weir A., "Renewable Energy Sources", 2nd Edition, EFN Spon Ltd., UK, 1986.
- 2. G.D. Rai, "Non-Conventional Energy Sources", 4th Edition, Khanna Publishers, New Delhi, 2009.
- 3. B.H.Khan, "Non-Conventional Energy Sources", Tata McGraw-Hill Education Private Limited, New Delhi.
- 4. S.Rao, Dr.B.B.Parulekar Energy Technology(Non-conventional, Renewable and Conventional), Khanna Publishers, Delhi.
- 5. S.Hasan Saeed, D.K.Sharma, "Non –conventional energy Resources", 3rd Edition, S.K.Kataria& Sons, 2012.

Web Resources:

1. www.renewable-energy-sources.com/

The break-up of CIE: Internal Tests + Assignments + Quizzes

1	No. of Internal Tests:	02	Max. Marks for each Internal Tests:	30
2	No. of Assignments:	03	Max. Marks for each Assignment:	05
3	No. of Quizzes:	03	Max. Marks for each Quiz Test:	05
	Duration of Internal Test:	90 Mir	nutes	

IBRAHIMBAGH, HYDERABAD – 500 031 Department of Mechanical Engineering

SUPPLY CHAIN MANAGEMENT (PE-III)

SYLLABUS FOR B.E.VIII-SEMESTER

L:T:P(Hrs/week): 3:0:0	SEE Marks:60	Course Code: U21PE830ME
Credits: 03	CIE Marks:40	Duration of SEE: 03Hours

COURSE OBJECTIVE The objective of the course is to	COURSE OUTCOMES On completion of the course, students will be able to
know the significance of supply chain management in engineering, maintain inventory and pricing.	 Discern what supply chain management concepts are used in engineering applications. Understand why planning an effective transportation and warehouse management systems is essential. Know how to Design effective supply chain networks.
	4 Tell how to Integrate and optimize demand and supply gaps.5 Design pricing and revenue management systems

	CO-PO and CO-PSO mapping														
CO		PO mapping PSO mapping										oing			
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1		1										2	1		
CO2			2											1	
CO3									1			1		1	
CO4											1				
CO5												2			1

UNIT-I: INTRODUCTION-SUPPLY CHAIN MANAGEMENT (SCM)

What is supply chain?, types of supply chains, major drivers of supply chain; objectives and importance of SCM, structure of a supply chain, drivers of supply chain performance, roles of facilities, inventory, transportation, information, and pricing in SCM. Examples of supply chains. Case study: Seven-Eleven Japan Co.

UNIT-II: DESIGNING SUPPLY CHAIN NETWORK

Design options for distribution network, online sales and the distribution network, role of network design in the supply chain, factors influencing network design decisions, impact of globalization on supply chain networks.

UNIT-III: PLANNING DEMAND AND SUPPLY IN A SUPPLY CHAIN

Demand forecasting in a supply chain, role of forecasting, time-series forecasting methods, measures of forecast error, aggregate planning, and aggregate planning strategies, Supply chain planning, demand planning and forecasting operational practices in supply chain, Just-in-time, Kanban, Vendor-managed inventory, managing supply & demand,

UNIT-IV: PLANNING AND MANAGING INVENTORIES IN A SUPPLY CHAIN

Classification of inventory, role of cycle inventory in supply chain, control of inventories in retail and services, economies of scale to exploit fixed costs and quantity discounts, short-term discounting: Trade promotions, managing uncertainty: safety inventory and optimal level of product availability.

UNIT-V: DESIGNING AND PLANNING TRANSPORTATION NETWORKS: Role of transportation in supply chain, modes of transportation and their performance characteristics, design options for a transportation network, Mumbai Dabbawalla's: A highly responsive distribution network. Sourcing Decisions in Supply Chain: Role of sourcing in a supply chain, Inhouse or outsource, supplier selection-auctions and negotiations.

Learning Resources:

- 1. Sunil Chopra & Peter Meindl, "Supply Chain Management Strategy, Planning and Operation", 6th Edition, Pearson India Education Services Pvt. Ltd., 2018.
- N. Chandrasekaran, "Supply Chain Management Process, System, and Practice", Oxford University Press, 2010.
- 3. R. P. Mohanty, S. G. Deshmukh, "Supply Chain Management Theory & Practices", Biztantra, New Delhi, 2010.
- 4. Martin Christopher, "Logistics & Supply Chain Management", 5th Edition, Financial Times Series, 2010.
- 5. Dobler Donald. W, David N.Burt, "Purchasing &Supply Management Text & Cases", McGraw-Hill, 1996.
- ChitaleK. Gupta R.C, "Materials Management-Text and Cases", Prentice-Hall of India Pvt. Limited, 2007.

Web Resources:

- 1. NPTEL :: Management Operations and Supply Chain Management
- 2. NPTEL :: Management NOC: Supply Chain Analytics

The break-up of CIE: Internal Tests+ Assignments + Quizzes

- 1 No. of Internal Tests: 02 Max.Marks for each Internal Test: 30
- 2 No. of Assignments: 03 Max. Marks for each Assignment: 05
- 3 No. of Quizzes: 03 Max. Marks for each Quiz Test: 05 Duration of Internal Test: 90 Minutes

IBRAHIMBAGH, HYDERABAD – 500 031 Department of Mechanical Engineering

COMPOSITE MATERIALS (PE-IV)

SYLLABUS FOR B.E.VIII-SEMESTER

L:T:P(Hrs/week): 3:0:0	SEE Marks:60	Course Code: U21PE840ME
Credits: 03	CIE Marks:40	Duration of SEE: 03Hours

COURSE OBJECTIVE	COURSE OUTCOMES										
The objective of the	On completion of the course, students will be able to										
course is to											
understand the basic principles and importance of composite materials and analyse the micro and macro mechanics of composite materials.	 understand the importance of composite materials in Engineering applications interpret the manufacturing of composites analyse the composites for various elastic constants at macro level and micro level understand the basic theories of failures associated with composites. estimate and Calculate the strength of laminated 										
	composites.										

	CO-PO and CO-PSO mapping														
CO		PO mapping											PSO mapping		
	1	L 2 3 4 5 6 7 8 9 10 11 12 1 2 3													
CO1	3	2	1	1	2							2	3	2	2
CO2	3	2	1	1	2							2	3	2	2
CO3	3	2	1	1	2							2	3	2	2
CO4	3	2	1	1	2							2	3	2	2
CO5	3	2	1	1	2							2	3	2	2

UNIT-I: INTRODUCTION

Definition and classification of Composites (PMC, MMC, CMC), FRP Composites, Fiber Reinforcements: Fiber Types and its properties, Fiber Forms, matrix materials and its properties: Thermoset Matrices, Thermoplastic matrices, Applications of Composite Materials.

UNIT – II

Manufacturing Processes: Hand– Lay– Up, Spray technique Bag Molding, Autoclave processing, compression Molding, Resin Transfer Molding, Pultrusion, filament winding,

UNIT-III: MICROMECHANICS OF COMPOSITES

Basic concepts: Volume and Mass fraction, Heterogeneous, Anisotropic, Orthotropic, Transversely Isotropic and Isotropic Materials. Mechanical Properties: Prediction of Elastic constants, micromechanical approach, Halpin– Tsai equations.

UNIT-IV: MACRO MECHANICS OF COMPOSITES

Elastic constants of a lamina, relations between engineering constants and reduced stiffness and compliances, variation of lamina properties with orientation, Classification of Laminated composites, analysis of laminated composites, stresses and strain with orientation,

UNIT-V: STRENGTH OF ORTHOTROPIC LAMINA

Tensile and compressive strength of unidirectional fiber composites, fracture modes in composites, delamination failure, Maximum stress theory, maximum strain theory Tsai– Hill Criterion, Tsai– Wu Criterion.

Learning Resources:

- 1. Madhujit Mukhopadhyaya, "Mechanics of Composite Materials and Structures", Universities Press, 2004
- 2. Ronald F.Gibson, "Principles of composite Materials Mechanics", McGraw– Hill Inc, 1994.
- 3. Krishna, K.Chewla. "Composite materials", Springer– Verlag, 1987.
- 4. Carl. T.Herakovich, "Mechanics of Fibrous Composites", John Wiley sons inc., 1998
- 5. Ever J.Barbero, "Introduction to composite Materials Design", Taylor & Francis, 1999.
- 6. Jones, R.M., "Mechanics of composite Materials", McGraw– Hill Inc. 1967.

The break-up of CIE: Internal Tests+Assignments + Quizzes

- 1No. of Internal Tests:02Max.Marks for each Internal Test:302No. of Assignments:03Max. Marks for each Assignment:053No. of Quizzes:03Max. Marks for each Quiz Test:05
 - Duration of Internal Test: 90 Minutes

IBRAHIMBAGH, HYDERABAD – 500 031 Department of Mechanical Engineering

POWER PLANT ENGINEERING (PE-IV)

SYLLABUS FOR B.E.VIII-SEMESTER

L:T:P(Hrs/week): 3:0:0	SEE Marks:60	Course Code: U21PE850ME
Credits: 03	CIE Marks:40	Duration of SEE: 03Hours

COURSE OBJECTIVE The objective of the course is to	COURSE OUTCOMES <i>On completion of the course, students will be able to</i>
impart knowledge on various sources of energy, types of power plants, their working and economics of power generation.	 describe various sources of energy, working of steam power plant and fuel handling equipment. Explain combustion processes, ash handling systems and cooling towers of steam power plant. analyze principles and working of hydro-electric power plant. describe principles and working of nuclear power plant. estimate the cost of power generation and the environmental effects of power plants.

	CO-PO and CO-PSO mapping															
CO		PO mapping												PSO mapping		
	1	1 2 3 4 5 6 7 8 9 10 11 12 1 2 3														
CO1	3	2	2			2	2	2		2			3	2	1	
CO2	3	2	2			2	2	2		2			3	2	1	
CO3	3	2	2			2	2	2		2			3	2	1	
CO4	3	2	2			2	2	2		2			3	2	1	
CO5	3	2	2			2	2	2		2			3	2	1	

UNIT – I

Introduction to sources of Energy: Resources and development of Power in India. Principles of power generation for various conventional and non-conventional power plants.

Steam Power plant: selection of site for a thermal power plant, Plant Layout, Working of different circuits, Types of Coal, Coal Handling, Fuel handling equipment.

UNIT-II

Combustion Process: Overfeed and underfeed fuel beds, Travelling grate stokers, Spreader stokers, Retort stokers, Pulverized fuel burning systems and its components, working principle of Cyclone furnace, Ash Handling Systems, draught system, Dust collectors.

Working principle of Cooling Towers

UNIT-III: HYDRO ELECTRIC POWER PLANT

Hydroelectric Power Plant:

Water Power, Hydrological Cycle, measurement of run-off, selection of site for a hydro electric power plant, Essential features of a hydro power plant. Hydrographs, Flow duration curve and mass curve-related numerical problems.

UNIT-IV: NUCLEAR POWER PLANT

selection of site for a nuclear power plant, Nuclear fuels, conversion and breeding, fertile materials, methods of enriching uranium, Nuclear Reactors, working of reactors, Pressurized water reactor, Boiling Water Reactor, Sodium Graphite Reactor, Fast Breeder Reactor, Gas cooled Reactor, Radioactive waste disposal.

UNIT-V

Power plant Economics and Environmental considerations

Capital cost, Investment of fixed charges, Operating costs, General arrangement of power distribution, Load curves, Average Load and Load Factor, Delivery Factor, Related exercises.

Effluents from Power plants and impact on environment

Pollutants and Pollution standards, Methods of Pollution control.

Learning Resources:

- Rajput, R.K, "A Text Book of Power Plant Engineering', 5THEdition, Laxmi Publications, New Delhi,2016.
- 2. Arora S.C, Domukundwar S, "A Course in Power Plant Engineering", Dhanapat Rai &Sons, New Delhi, 2005
- 3. P C Sharma, "A Text Book of Power Plant Engineering", S K Kataria& Sons, 2013
- 4. Nag P.K, "Power Plant Engineering", 2nd Edition, Tata Mc Graw Hills Co. Ltd., New Delhi, 2002.
- 5. Wakil M.M, "Power Plant Technology", Mc Graw Hill publications, New York, 2005.

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The break-up of CIE: Internal Tests+Assignments + Quizzes 1 No. of Internal Tests: 02 Max Marks for each Internal Test:

-				30
2	No. of Assignments:	03	Max. Marks for each Assignment:	05
3	No. of Quizzes:	03	Max. Marks for each Quiz Test:	05
	Duration of Internal Test:	90 Mir	nutes	

IBRAHIMBAGH, HYDERABAD – 500 031 Department of Mechanical Engineering

PRODUCTION AND OPERATIONS MANAGEMENT (PE-IV)

SYLLABUS FOR B.E.VIII-SEMESTER

L:T:P(Hrs/week): 3:0:0	SEE Marks:60	Course Code: U21PE860ME
Credits : 03	CIE Marks:40	Duration of SEE: 03Hours

COURSE OBJECTIVES	COURSE OUTCOMES
The objectives of this	On completion of the course, the student will
course are to:	be able to:
study the types of plant	1. Classify the types of plant layouts, production
layout, forecasting	systems based on product using the facilities
methods, cost analysis,	the plant
human resource	2. Estimate the future demand using forecasti
management quality	methods through qualitative and quantitati
control.	models
	3. Determine the requirement of resources
	minimise the total cost using aggrega
	planning techniques.
	4. Selection of right to the right job to suital
	pay for the human resources.
	5. Importance of quality and checking the proce
	capability.

	CO-PO and CO-PSO mapping														
CO		PO mapping											PSO mapping		
	1	1 2 3 4 5 6 7 8 9 10 11 12 1 2 3													
CO1	3	2		1							1	2	3	1	1
CO2	3	2		2							2	2	3	1	1
CO3	3	2		2							2	2	3	2	1
CO4	3	2		3							2	2	3	1	1
CO5	3	2		1							3	2	3	2	2

Unit-I

Production & Operations Management: Introduction, Types of Production Systems – Job shop, Batch, Flow shop. Types of business organizations and organization structures. Calculations on productivity. Capacity planning and process planning calculations Plant location and layout: Factors affecting plant location, plant layout objectives, types of layouts, merits and demerits.

Unit-II

Forecasting: Introduction, forecasting objectives and uses, demand patterns, qualitative models – market survey, delphi, quantitative models – moving average, weighted moving average, simple exponential smoothing, trend adjusted exponential smoothing, least square method, simple regression, multiple regression. Forecast Errors: mean absolute deviation (MAD), mean square error (MSE), Mean Forecast Error (MFE), mean absolute percentage Error (MAPE)

Unit-III

Aggregate planning and master scheduling: Introduction, objectives of aggregate planning, cost in aggregate planning, strategies in aggregate planning, master production scheduling. Materials requirement planning MRP: Importance of MRP, MRP system inputs and outputs, MRP calculations. Calculations of net amount required(units) and planned order releases in BOM structures.

Unit-IV

Human resource management: Concept and objectives, man power planning, recruitment and selection, training and developments, wages and incentives methods. Industrial acts

Unit-V

Quality and reliability: Definition of quality, objectives, cost of quality and value of quality. Acceptance sampling, Statical process control, process variability, Control charts for variables and attributes. Definition of reliability bath tub curve and estimation of reliability for different systems

Learning Resources:

- 1. Joseph Monk," Operations Management", TMH Publishers, New Delhi, 2004
- 2. Buffa Elwood S," Modern Production / Operations Management", John Wiley Publishers, Singapore, 2002
- 3. Everett, E. Adam. Jr and Ronald. J. Ebert, "Production and operations management: concepts, models and behaviour " Prentice Hall of India Pvt. Ltd., New Delhi, 5th ed. 1998.
- 4. Garry Desseler: Human resource management, pearson education.
- 5. Montgomory "Statistical Process control", PHI.

The break-up of CIE: Internal Tests+Assignments + Quizzes

1 No. of Internal Tests: Max.Marks for each Internal Test: 02 30 2 No. of Assignments: 03 Max. Marks for each Assignment: 05 3 No. of Ouizzes: 03 Max. Marks for each Quiz Test: 05 Duration of Internal Test: 90 Minutes

IBRAHIMBAGH, HYDERABAD – 500 031 Department of Mechanical Engineering

Project /Internship

SYLLABUS FOR B.E.VIII-SEMESTER

L:T:P(Hrs/week)::0:0:12	SEE Marks:50	Course Code: U21PW819ME
Credits: 6	CIE Marks:50	Duration of SEE:

COURSE OBJECTIVE	COURSE OUTCOMES
The objective of the course	On completion of the course, students will be
is to	able to
solve a real life problem	1. define the problem by literature study.
related to Mechanical	2. design and conduct experiments using
engineering using relevant	Mechanical Engineering tools to collect
tools and techniques, write	data.
a thesis and give a	3. analyze and interpret data using graphs.
presentation.	4. make logical conclusions to justify the
	results.

	CO-PO and CO-PSO mapping														
CO		PO mapping PSO mapping												oing	
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	3											3	3	3	2
CO2		3	3	2	3							3	3	2	3
CO3					3	3	3	1	1	3		3	1	2	2
CO4	2	1								3	3	3	1	2	3

The department will appoint a project coordinator who will be in-charge of the following.

- Grouping of students (Maximum of 3 in a group)
- Allotment of project guide
- Project progress monitoring at regular intervals
- Attendance monitoring for those students doing project in Industry/Internship.

The project allotment should be completed by the IV week of VII semester so that students get enough time for completion of their project.

All the projects are to be checked for progress at least twice in a semester. CIE marks (50 marks) are based on the performance in the two presentations which are awarded by a committee based on project rubrics.

The SEE marks (50 marks) are awarded by an external examiner based on a viva-voce exam.

With effect from the Academic Year 2024-25

Norms of final documentation of the project report will be provided by the Department.

No. of Presentations for	2	Max. Marks for each CIE	25					
CIE marks								
Marks are awarded based on literature study, technical details, presentation								
and conclusions using rubrics.								
Duration of Presentation: 20 min								

VASAVI COLLEGE OF ENGINEERING (AUTONOMOUS) <u>SCHEME OF INSTRUCTION AND EXAMINATION (R-21)</u> <u>B.E. (ME) Honours Degree Program in Robotics</u> (2024-2025)

	B.E (ME) Honou	urs D	egre	ee in	Robotics							
			heme truct		Scheme of Examination							
S. No.	Name of the Course		ours p Week		Duration	Maxii Ma		dits				
		L	т	Р	in Hrs	SEE	CIE	Credits				
THEORY CUM PRACTICALS												
VII-Semester AY 2024-25												
U21PC760ME	Robotics and Control	3	-	-	3	60	40	3				
U21PC731ME	Robotics Lab	-	-	2	3	50	30	1				
U21PW729ME	Course Project	-	-	6	3	50	50	3				
	TOTAL	3	0	8		160	120	7				
	GRAND TOTAL		11		280			7				
NPTEL Course	(Robotics related): 12	wee	ks du	ratio	ns(V or VI	-Semes	ster)	3				

IBRAHIMBAGH, HYDERABAD – 500 031 Department of Mechanical Engineering

ROBOTICS AND CONTROL

SYLLABUS FOR B.E. VII-SEMESTER

SEE Marks : 60 Course Code : U21PC760ME
CIE Marks: : 40 Duration of SEE : 3 Hours
 COURSE OUTCOMES On completion of the course, students will be able to Analyze the kinematics of robotic systems and apply them to solve real world problems Apply differential kinematics and static concepts to design and control robotic systems Analyze the dynamics of serial manipulators using lagrangian and Newton-Euler mechanics Develop motion and force control strategies for robotic systems using feedback control techniques Generate and analyze robot trajectories for

	CO-PO and CO-PSO mapping														
CO		PO mapping PSO mapping											apping		
	1	1 2 3 4 5 6 7 8 9 10 11 12 1 2 3													
CO1	2	2	2			2			2	2		2	3	2	1
CO2	2	2	2			2			2	2		2	ŝ	2	1
CO3	3	3	3			З			ŝ	ŝ		2	ŝ	2	1
CO4	3	2	2		3	З		ŝ	2	2	З	3	З	2	1
CO5	2	2	2		2	2		2	2	2	2	2	3	2	1

UNIT-I Robot Kinematics

Forward Kinematics: Forward/direct kinematic analysis of serial manipulators. Inverse Kinematics: General properties of inverse kinematic solution. Inverse kinematics of serial RR planar manipulators.

UNIT-II

Differential Kinematics and Statics

Linear and angular velocity of links, Velocity propagation, Manipulator Jacobian for serial manipulators, Jacobian Singularities, Static Analysis: Force and moment balance, Jacobian in statics.

UNIT-III

Dynamics of serial manipulators

Lagrangian formulation for equations of motion for RP, RR serial manipulators, Recursive dynamics using Newton-Euler formulation of RP and RR serial manipulator.

UNIT-V

Motion and Force Control:

Decentralized Control: Independent joint control, Decentralized feed forward compensation, computed torque control

Centralized control: ID control with granty compensation

Force Control: Passive and active compliance impedance control

Force control with inner position loop, inner velocity loop, parallel force / position control.

UNIT-V

Trajectory Generation

Joint-Space Techniques: Cubic Polynomial Trajectories, Linear Segments with Parabolic Blends-without and with via points

Cartesian-Space Techniques: Straight line path, Circular Path, Position Planning, Orientation Planning.

Learning Resources:

- 1. Bruno Siciliano, Lorenzo Sciavicco, Luigi Villani, Giuseppe Oriolo, "Robotics: Modelling, Planning and Control", Springer Science & Business Media, 2010.
- 2. M.W.Spong and M. Vidyasagar, "Robot Dynamics and Control", 1st Edition, John Wiley and sons,1990.
- 3. R.K.Mittal and I.J. Nagrath, "Robotics and Control", Tata McGraw-Hill, 2003.
- 4. Subir Kumar Saha, "Introduction to Robotics", Tata McGraw-Hill Education, 2014.
- 5. Howie M. Choset, Seth Hutchinson, Kevin M. Lynch, "Principles of Robot Motion: Theory, Algorithms, and Implementation", MIT Press, 2005.

The break-up of CIE: Internal Tests + Assignments + Quizzes

- 1 No. of Internal Tests: 02
- Max. Marks for each Internal Test: 30
- No. of Assignments: 03 Max. Marks for each Assignment: 10
 No. of Quizzes: 0 Max. Marks for each Quiz Test: Duration of Internal Test: 90 Minutes

IBRAHIMBAGH, HYDERABAD – 500 031 Department of Mechanical Engineering

ROBOTICS LAB

SYLLABUS FOR B.E. VII-SEMESTER

Instruction : 2 Hours /week	SEE Marks	: 50	Course Code : U21PC731	ME
Credits : 1	CIE Marks:	: 30	Duration of SEE : 2 Hou	Irs

COURSE OBJECTIVE	COURSE OUTCOMES						
The objective of the course is	On completion of the course, students will be able						
to	to						
model, analyses different types of industrial robotics using CAD software and 6DOF serial manipulator.	Modelling of various industrial robotics using ADAMS software. Designing and controlling of robotic path using various sensors. Analyses of forward and inverse kinematics of industrial manipulator using 6-dof serial manipulator						

	CO-PO and CO-PSO mapping														
CO		PO mapping PSO mapping													
	1	1 2 3 4 5 6 7 8 9 10 11 12 1 2 3													
CO1	1	3		1	3							2	1	3	2
CO2	1		3	1	3							2	1	3	2
CO3	1	1 3 1 3 2 1 3 2													

List of Experiments:

- 11. Modelling of 6 DOF anthropomorphic arm in ADAMS.
- 12. Simulation of 6 DOF anthropomorphic arm in ADAMS.
- 13. Forward kinematic analysis of 4 DOF SCARA Robot using MATLAB (Simscape Multi-body)
- 14. Inverse kinematic analysis of 4 DOF SCARA Robot using MATLAB (Simscape Multi-body)
- 15. Assembling of robot mechanical components mounting of motors, sensors, electronic circuits to the chassis
- 16. Navigation and obstacle avoidance robot using ultrasonic sensor
- 17. Navigation and obstacle avoidance robot using computer vision
- 18. Programming and controlling a line follower robot using IOT
- 19. Trajectory planning and navigation of an autonomous rover
- 20. Forward kinematic analysis of 6-DOF serial manipulator
- 21. Inverse kinematic analysis of 6-DOF serial manipulator

- 22. Forward kinematic analysis of 6-DOF Parallel manipulator
- 23. Inverse kinematic analysis of 6-DOF parallel manipulator
- 24. Assembling of drone using mechanical components mounting of motors, sensors, electronic circuits

Note: Any 12 Experiments can be conducted

The break-up of CIE: Internal Tests + Assignments + Quizzes

No. of Internal Tests:	01	Max. Marks for Internal Test:	12					
Marks for day-to-day laboratory class work 18								
Duration of Internal Test: 3Hours								

IBRAHIMBAGH, HYDERABAD – 500 031 Department of Mechanical Engineering

Course Project

SYLLABUS FOR B.E.VII-SEMESTER

L:T:P(Hrs/week)::0:0:6	SEE Marks: 50	Course Code: U21PW729ME
Credits: 3	CIE Marks: 50	Duration of SEE: 3 Hours

COURSE OBJECTIVE	COURSE OUTCOMES
The objective of the course is to	On completion of the course, students will be able to
Design and develop a prototype related to robotics engineering using relevant tools and techniques, write a report and give a presentation.	 define and design the robotics problem by literature study. analyze by conducting experiments and obtain relevant data. develop a prototype / working model using the data obtained. to work in teams and adapt for the advanced technological changes make logical conclusions to justify the results.

	CO-PO and CO-PSO mapping														
CO		PO mapping PSO mapping											ing		
	1	1 2 3 4 5 6 7 8 9 10 11 12 1 2 3													
CO1	3											3	3	3	2
CO2		3	3	2	3							3	3	2	3
CO3					3	3	3	1	1	3		3	1	2	2
CO4									3	2	3	2	1	2	2
CO5	2	1								3	3	3	1	2	3

The department will appoint a project coordinator who will be in-charge of the following.

- Grouping of students (Maximum of 3 in a group)
- Allotment of project guide
- Project progress monitoring at regular intervals
- Attendance monitoring for those students doing project in Industry.

Project topics may be chosen by the student with advice and approval from the faculty members. Students are to be assessed and evaluated as per the following criteria.

- Problem definition based on literature study.
- Usage of modern tools.
- Analysis of the problem under consideration.
- Fabrication of the model / prototype.
- Results and conclusions.
- Team Work, Report writing & Presentation with ethics
- Project Management

Each student is required to:

- 1. Submit a one-page synopsis in the beginning of project work for display on the notice board.
- 2. Give a 20 minutes presentation through LCD power point presentation followed by a 10 minutes discussion.
- 3. Submit a report on the project work with list of references and slides used.

The project allotment should be completed by the IV week of VII semester so that students get enough time for completion of their project.

All the projects are to be evaluated for progress at least twice in a semester. CIE marks (30 marks) are based on the performance in the two presentations which are awarded by a committee based on project rubrics.

The SEE marks (50 marks) are awarded by an external examiner based on a viva-voce exam.

Norms of final documentation of the project report will be provided by the Department.

No. of Presentations for	2	Max. Marks for each CIE	15						
CIE marks presentation:									
Marks are awarded based on literature study, usage advanced tools, prototype									
development, presentation a	development, presentation and conclusions using rubrics.								
Duration of Presentation: 20 min									